# Ruitao Wu

	Personal Page   GitHub   LinkedIn 333 W GARVEY AVE # 1008 MONTEREY PARK, CA 91754 626-267-3098 Private: ruitaowu0@gmail.com   Work: rwu9937@sdsu.edu		
	Thvate. Tultaowab@giliail.com   Work. Twa557@5d5d.cdu		
Interested Area	Natural Language Process, Object detection and classification, Synthetic Data generation Software Engineer, Generative adversarial networks, Generative Pre-trained Transformer		
ACADEMIC BACKGROUND	M.S. Computer Science San Diego State University, San Diego, California	2024	
	B.S. Computer Science California State University, Northridge, Northridge, CA	2022	
	N/A Mathematics East Los Angeles College Monterey Park, CA	2019	
EMPLOYMENT HISTORY	Software Developer The SysteMs And InteLligEnce (SMILE) Laboratory, San Diego, CA • Leading a group to design an unmanned aerial vehicle(UAV) cont	SP23 – NOW rol system	
	• Base on robot operating system(ROS) design graphical user interfa- to send command over GUI to UAV	ce(GUI) allows user	
	Research Assistant2021 - 2022The Autonomy Research Center for STEAHM (ARCS), Northridge, CA• Participant in various reserach project in field of Computer Science and Engineering		
	• Working on Using openCAESAR and INTREPID to design and additively manufacture the Multiphysics optical tracker Project Intro		
	• Design vocabulary and ontology for project implement by ontology as well as the flowchart of the project	modeling language	
PROJECT	Multimodal Data Generation	SP23—NOW	
	Software Deveoper		
	• Participate research project in synthetic data generation		
	• Participate multimodal data generation project		
	• Synthetic text and image data generation which include: text-to-text and text-to- image		
	Robot Operating System based Graphical User Interface	SP23—NOW	
	<ul> <li>Primary Software Engerneer/Core Deveolper</li> <li>Design a graphical user interface(GUI) based on robot operating system</li> </ul>		
	• Develop an application user interface that allows a user to access the GUI and control an unmanned aerial vehicle(UAV)		
	• Develop UAV control and mission plan that allows UAV to accomplish different task		
	Senior Design CalTrans Project	2021/08 - 2022/05	
	Leader/data process/database design		

• Leading a group to develop real-time vehicle detection and classification system

- Use YOLO3(YOU ONLY LOOK ONCE version 3) trained a customer machine learning model that could classify Six types of vehicle
- Bring out an enhanced and powerful model in vehicle classification in real-time system compare to all other YOLO model

## Multiphysics optical tracker

## 2021/6 - 2022/06

06/21 - 07/21

#### CSUN ARCS Developer/Programmer

- Use ontology modeling language to build an ontology for the project in openCAESAR
- Define discipline and application vocabularies for the project. Integrate existing vocabularies, such as foundation and core vocabulary.
- Define description for each project component, such as thermal analysis, general design optimization, and topology optimization.
- Use SPARQL for data retrieve on the Apache Jena Fuseki server
- Design and implement a web application to demonstrating and format the SPARQL query result

### Snakebyte Transpiler

#### Programmer

- Design a compiler that implement Java language target Python language
- Added more than **2000 Lines** of test code which achieve code coverage above 90%
- The compiler includes the following parts: parser, lexcer, typechecker, and code generator GitHub

Skills	• Java, JavaScript, C/C++, Python, HTML/CSS, Git, Machine Learning, Sklearn, YOLO, Keras/TensorFlow/PyTorch, MySQL, ROS			
MEMBERSHIP	NASA – The Autonomy Research Center for STEAHM, Student Fellow Association for Computing Machinery, Student Member Institute of Electrical and Electronics Engineers, Student Member Laboratory for Sustainable and Additive Manufacturing, Alumni The SysteMs And InteLligEnce (SMILE) Laboratory,Group Member			
Pulicashion	<b>R. Wu</b> , et al. "Real-time Vehicle Detection System for Intelligent Transportation using Machine Learning," 2022 IEEE Green Energy and Smart System Systems(IGESSC), 2022, pp. 1-6, doi: 10.1109/IGESSC55810.2022.9955329.			
Conference Presentation	IEEE Green Energy and Smart Systems Conference, LONG BEACH, CA,2022IEEE Green Energy and Smart Systems Conference–Student Poster Competition Session2022Subject Vehicle Detection for Real-time Traffic Flow using Machine Learning2021			
	<ul> <li>CSU, Northridge's Autonomy Research Center for STEAHM poster presentation at JPL 2022</li> <li>Subject Subject: Digital Twin Integration of openCAESAR and INTREPID to design and additively manufacture the Multiphysics Optical Tracker</li> </ul>			

HONORS	Dean's List	Fall 19   Fall 20	Spring 20	
AWARDS	Senior Design Showcase First place in Computer Science Dep	artment	Spring 22	
	Oral Presentation 3D Object Detection and Vehicle Classification based on LiDAF			
	Clouds to Monitor Real-time Traffic Flow			
Volunteer	The Orange County Food Bank Package food in warehouse		2019	